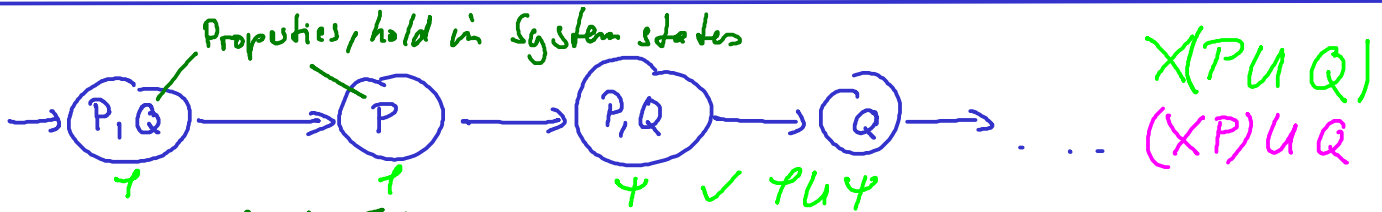
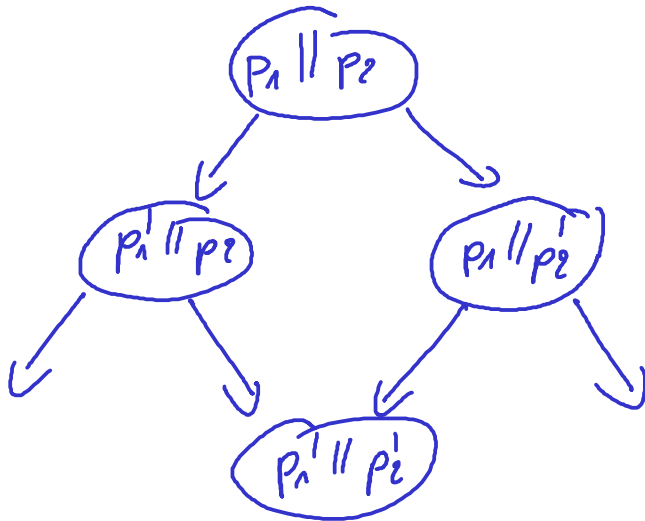
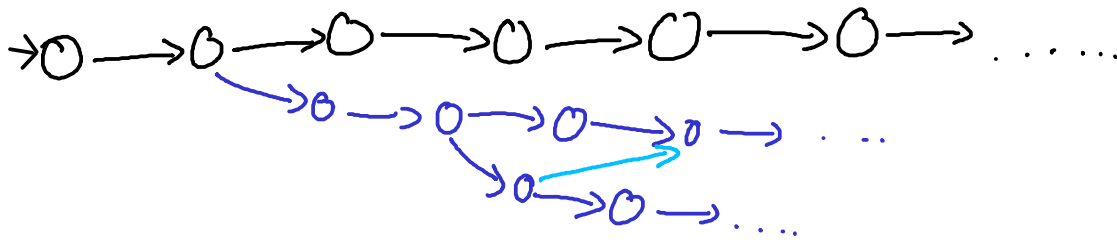


Linear Time Logic (LTL):



Syntax of LTL:

$P \in Prop \Rightarrow P \in LTL$  , true, false  $\in LTL$

$\neg, \psi \in LTL \Rightarrow \neg \neg \psi, \psi \vee \psi, \psi \wedge \psi \in LTL$

$\Rightarrow X\psi, \psi U \psi \in LTL$   
 Next                      Until

Abbreviations:

$F\psi := true U \psi$

$G\psi := \neg F\neg\psi$

$F^\infty\psi := G F\psi$

$G^\infty\psi := F G\psi$

Finally — liveness

Globally — safety

Infinitely often  $\psi$  holds

$\psi$  hold always with finitely many exceptions

for fairness of the as preconditions

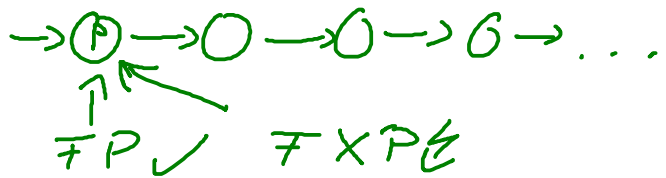
## Semantics:

It's defined for an infinite path  $\pi = p_0 p_1 p_2 \dots$  with  $p_i \in \mathcal{P}(\text{Prop})$  ( $\pi \in \mathcal{P}(\text{Prop})^\omega$ ).

- $p_0 \pi \models P$  iff  $P \in p_0$        $p_0 \pi \models \neg P$  iff  $P \notin p_0$
- $\pi \models \varphi \wedge \psi$  iff  $\pi \models \varphi$  and  $\pi \models \psi$
- $\pi \models \varphi \vee \psi$  iff  $\pi \models \varphi$  or  $\pi \models \psi$
- $\pi \models \neg \varphi$  iff  $\pi \not\models \varphi$
- $p_0 \pi \models X\varphi$  iff  $\pi \models \varphi$
- $\pi \models \varphi U \psi$  iff  $\exists i \in \mathbb{N} : \forall j < i : p_j p_{j+1} \dots \models \varphi$  and  $p_i p_{i+1} \dots \models \psi$
- $\pi \models F\varphi$  iff  $\exists i \in \mathbb{N} : p_i p_{i+1} \dots \models \varphi$
- $\pi \models G\varphi$  iff  $\forall i \in \mathbb{N} : p_i p_{i+1} \dots \models \varphi$

## Equivalences on LTL:

FXP



$$FX\varphi \approx X F\varphi$$

$$\neg(\varphi \wedge \psi) \approx \neg\varphi \vee \neg\psi$$

$$\neg(\varphi \vee \psi) \approx \neg\varphi \wedge \neg\psi$$

$$\neg(\neg\varphi) \approx \varphi$$

$$\neg X\varphi \approx X(\neg\varphi)$$

$$\neg F\varphi \approx G\neg\varphi$$

$$\neg G\varphi \approx F\neg\varphi$$

$$\neg(\varphi U \psi) \approx (\neg\varphi) R (\neg\psi)$$

$$F\varphi \approx \varphi \vee X F\varphi$$

$$G\varphi \approx \varphi \wedge X G\varphi$$

$$\varphi U \psi \approx \varphi \vee (\varphi \wedge X(\varphi U \psi))$$

$$\varphi R \psi \approx \varphi \wedge (\varphi \vee X(\varphi R \psi))$$

Release operation, strange semantics but useful for negating Until.

enroll the fixed point to check for the initial state of path and to shift the remaining decision to the path starting in the next state.

use laws to push negation inside